

# İzmir Institute of Technology

# INSTITUTE OF ENGINEERING AND SCIENCE(M.S.) MECHANICAL ENGINEERING

| ME580 HAPTICS AND TELEOPERATION |                  |                           |     |        |                        |
|---------------------------------|------------------|---------------------------|-----|--------|------------------------|
| Semester                        | Course Unit Code | Course Unit Title         | L+P | Credit | Number of ECTS Credits |
| 1                               | ME580            | HAPTICS AND TELEOPERATION | 3   | 3      | 7                      |
| Mode of Delivery:               |                  |                           |     |        |                        |

Face to Face Language of Instruction: English Level of Course Unit: Second Cycle Work Placement(s): No

### Department / Program: MECHANICAL ENGINEERING

Type of Course Unit: Elective

## **Objectives of the Course:**

This course covers the field of haptics as it relates to creating touch feedback in simulated virtual environments and in teleoperation systems. It provides an introduction to bilateral teleoperation systems and haptic interfaces. Topics include haptic device design, classification of teleoperation systems, applications of teleoperation, master-slave telemanipulators, human-computer interaction, and parallel position/force and teleoperation controllers. **Teaching Methods and Techniques:** 

- Introduction to haptics - Haptics device design - Virtual Reality in haptics - Classification of teleoperation systems - Fault tolerance concept in teleoperation - Parallel position/force controllers - Teleoperation controllers

# Prerequisites and co-requisities:

### **Course Coordinator:**

### Name of Lecturers:

Asist Prof.Dr. MEHMET İSMET CAN DEDE Assistants:

### **Recommended or Required Reading**

Resources

G.C. Burdea, "Force and Touch Feedback for Virtual Reality," Wiley, 1st Edition, New York, 1996., T.A. Kern, "Engineering Haptic Devices: A Beginner s

| Week   | ly Detailed Course Contents   |   |           |
|--|---|---|-----------|
| Week   | Topics  | Study Materials   | Materials |
| 1<br>2<br>3<br>4<br>5<br>6<br>7<br>7<br>8<br>9<br>10<br>11<br>12<br>13<br>14<br>15<br>16 | Overview of course and robotics<br>Basics of haptics and telegogentation.es.<br>Terminology in haptics, incurpriseously and psychophysics<br>inducering the determined of the second secon | Study Materials     Materials       T.A. Kern, "Engineering Haptic Devices:     T.A. Kern, "Engineering Haptic Devices:       M.I.C. Dede, "Fault-Tolerant Teleoperati     T.A. Kern, "Engineering Haptic Devices:       T.A. Kern, "Engineering Haptic Devices:     T.A. Kern, "Engineering Haptic Devices:       T.A. Kern, "Engineering Haptic Devices:     T.A. Kern, "Engineering Haptic Devices:       T.A. Kern, "Engineering Haptic Devices:     T.A. Kern, "Engineering Haptic Devices:       T.A. Kern, "Engineering Haptic Devices:     T.A. Kern, "Engineering Haptic Devices:       T.A. Kern, "Engineering Haptic Devices:     T.A. Kern, "Engineering Haptic Devices:       T.A. Kern, "Engineering Haptic Devices:     T.A. Kern, "Engineering Haptic Devices:       T.A. Kern, "Engineering Haptic Devices:     T.A. Kern, "Engineering Haptic Devices:       T.A. Kern, "Engineering Haptic Devices:     T.A. Kern, "Engineering Haptic Devices:       T.A. Kern, "Engineering Haptic Devices:     T.A. Kern, "Engineering Haptic Devices:       M.I.C. Dede, "Fault-Tolerant Teleoperati     M.I.C. Dede, "Fault-Tolerant Teleoperati       M.I.C. Dede, "Fault-Tolerant Teleoperati     T.A. Kern, "Engineering Haptic Devices:       T.A. Kern, "Engineering Haptic Devices:     T.A. Kern, "Engineering Haptic Devices:       T.A. Kern, "Engineering Haptic Devices:     T.A. Kern, "Engineering Haptic Devices: |           |
| Cours  | e Learning Outcomes   |   |           |
| No   | Learning Outcomes   |   |           |
| C01<br>C02<br>C03<br>C04<br>C05<br>C06   | Ability to design haptic devices and teleperation systems<br>Ability to propose a design project related with haptics and teleoperation<br>Ability to conduct experiments with haptic devices and teleoperation systems<br>Ability to construct models of physical systems in virtual environment<br>Ability to compare and evaluate haptik device structures<br>Ability to present the design project among the peers and the instructor   |   |           |
| Progr  | ram Learning Outcomes   |   |           |
| No   | Learning Outcome  |   |           |
| P05<br>P06<br>P07<br>P04<br>P01  | To have advanced skills in scientific and technical writing and oral communicati<br>To have the ability to present his/her study in national or international congres<br>To have an appreciation of ethical values in scientific and technical studies.<br>To have the ability to identify, model, formulate, and solve mechanical enginee<br>To have advanced knowledge in the master thesis subject   | on.<br>ses, conferences and other scientific meetings.<br>ring problems in the field of research.   |           |

To have the ability to carry out independent research and study. To have the ability to use the knowledge learned in the courses. P02 P03

| Assessment Methods and Criteria |          |            |
|---------------------------------|----------|------------|
| In-Term Studies                 | Quantity | Percentage |
| Midterm exams                   | 0        | %0         |
| Quizzes                         | 0        | %0         |
| Homeworks                       | 0        | %0         |
| Other activities                | 0        | %0         |
| Laboratory works                | 0        | %0         |
| Projects                        | 3        | %60        |
| Final examination               | 1        | %40        |
| Total                           |          | %100       |
|                                 |          |            |

| ECTS Allocated Based on Student We   | orkload  |          |                 |
|--|----------|----------|-----------------|
| Activities   | Quantity | Duration | Total Work Load |
| Weekly Course Time   | 1        | 42       | 42              |
| Outside Activities About Course<br>(Attendance, Presentation, Midterm<br>exam,Final exam, Quiz etc.) | 1        | 90       | 90              |
| Application (Homework, Reading, Self<br>Study etc.)  | 0        | 0        | 0               |
| Laboratory   | 0        | 0        | 0               |
| Exams and Exam Preparations  | 1        | 27       | 27              |
| Total Work Load  |          |          | 159             |
| ECTS Credit of the Course  |          |          | 5               |
|  |          |          |                 |
|  |          |          |                 |

|  | Contribution | of Learning | Outcomes to | Programme | Outcomes |
|--|--------------|-------------|-------------|-----------|----------|
|--|--------------|-------------|-------------|-----------|----------|

Contribution: 0: Null 1:Slight 2:Moderate 3:Significant 4:Very Significant

|     | P01 | P02 | P03 | P04 | P05 | P06 | P07 |
|-----|-----|-----|-----|-----|-----|-----|-----|
| C01 | 2   | 2   | 2   | 4   |     |     |     |
| C02 |     | 2   |     | 2   | 4   |     |     |
| C03 | 2   | 2   | 2   | 4   |     |     |     |
| C04 | 2   |     | 2   | 4   |     |     |     |
| C05 | 2   | 2   | 2   | 4   |     |     |     |
| C06 |     | 2   | 2   |     | 4   | 2   | 1   |