

İzmir Institute of Technology

Faculty of Engineering Mechanical Engineering BS

ME469	Control Syst	em Design			
Semester	Course Unit Code	Course Unit Title	L+P	Credit	Number of ECTS Credits
7	ME469	Control System Design	3	3	5
Mode of Delivery: Face to Face Language of Instru English	ction:				

Level of Course Unit: First Cycle Work Placement(s): No Department / Program:

Mechanical Engineering BS Type of Course Unit:

Required **Objectives of the Course:**

The aim of this course is to teach the students the basic design methods of feedback control systems using root locus and frequency response techniques.

Teaching Methods and Techniques: Root Locus: - Basic Definition and Properties - Design in Feedback Control Systems Using Root Locus Technique Frequency Response: - Basic Definition, Properties - Bode Diagram -Nyquist Diagram and Nichols chart - Stability in Frequency domain - Design in Feedback Control Systems Using Frequency Response Technique Prerequisites and co-requisities:

Course Coordinator:

Name of Lecturers: Asist Prof.Dr. Mehmet İsmet Can Dede Assistants:

Recommended or Required Reading

Resources

Ogata K., 'Modern Control Engineering', Prentice Hall, 4. Ed, New Jersey, 2002, Dorf, R.C. and Bishop, R.H., Modern Control Systems, 12th Edition, Pear

Week '	Topics	Study Materials	Materials
	Root Locus:- Basic Definition and Properties		Ogata K., 'Modern Control Engineering
	Root Locus:- Basic Definition and Properties		Ogata K., 'Modern Control Engineerin
	Designing Control Systems Using Root Locus Technique		
	Designing Control Systems Using Root Locus Technique		
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	Designing Control Systems Using Root Locus Techniqu Designing Control Systems Using Root Locus Techniqu		
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	- requency Response:- Basic Definition and Properties- Bode Diagram- Nyquist Diagram and Nichols Chart- Stabilit requency Response:- Basic Definition and Properties- Bode Diagram- Nyquist Diagram and Nichols Chart- Stabilit	y in Frequ	Ogata K., 'Modern Control Engineering
0 1	Frequency Response:- Basic Definition and Properties- Bode Diagram- Nyquist Diagram and Nichols Chart- Stabilit	y in Frequ	Ogata K., 'Modern Control Engineering
	Designing Control Systems Using Frequency Response Technique		Ogata K., 'Modern Control Engineering
	Designing Control Systems Using Frequency Response Technique		Ogata K., 'Modern Control Engineerin
3 1	Designing Control Systems Using Frequency Response Technique Designing Control Systems Using Frequency Response Technique		Ogata K., 'Modern Control Engineerin Ogata K., 'Modern Control Engineerin
	Final 1st week		Ogata K., Modern Control Engineerin
	inal 1. week		
Course	Learning Outcomes		
10	Learning Outcomes		
01 02	Köklerin geometrik yeri grafiklerini olusturma ve yorumlayabilme becerisi Bir geribeslemeli kontrol sistemini köklerin geometrik yeri yöntemi ile tasarlama becerisi		
02 03			
04	Ability to design controllers of a feedback system by frequency response methods		
2.1	Ability to design controllers of a recebuck system by neducity response methods		
Progra	m Learning Outcomes		
lo	Learning Outcome		
03	To have the ability to use modern technical tools which are necessary for engineering applications and to e	fficiently implement information technol	ogies.
02	To have the ability to use modern technical tools which are necessary for engineering applications and to e To be able to design a complicated system or device that can satisfy the requirements under realistic condi	tions; to have the ability to use modern	design methods for that purpose.
04	To have the ability to detect, define, formulize and solve complicated engineering problems. To have the ability to design experiments, analyze and interpret results in order to examine engineering pro		
06			
05	To be able to choose and apply modeling and analysis methods for the encountered problems. To have the ability of modeling and solving engineering problems, using the acquired information about ma		
01 08			
08 07	To have the ability to work in disciplinary and interdisciplinary teams efficiently.		
	To be able to act conscious for the necessity of innovation and lifetime-learning: to have the ability of self-		

- To be able to act conscious for the necessity of innovation and lifetime-learning; to have the ability of self-renewal and to follow the progress. To be able to have tendency to the applications in professional life and creativity. To have the ability to act with a sense of professional and ethical responsibility; and with environmental and safety concerns.
- P09 P11 P10

Assessment Methods and Criteria				
In-Term Studies	Quantity	Percentage		
Midterm exams	1	%20		
Quizzes	4	%20		
Homeworks	0	%0		
Other activities	0	%0		
Laboratory works	0	%0		
Projects	1	%20		
Final examination	1	%40		
Total		%100		

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C02 C03

C04

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ECTS Allocated Based on Student Workload				
Activities	Quantity	Duration	Total Work Load	
Weekly Course Time	1	30	30	
Outside Activities About Course Attendance, Presentation, Midterm exam,Final exam, Quiz etc.)	1	60	60	
Application (Homework, Reading, Self Study etc.)	0	0	0	
Laboratory	0	0	0	
Exams and Exam Preparations	1	30	30	
Total Work Load			120	
ECTS Credit of the Course			5	

Contribution of Learning Outcomes to Programme Outcomes								
Contrit	oution	: 0: N	lull 1:	:Slight	t 2:M	odera	te 3:5	:Significant 4:Very Significant
	P01	P02	P03	P04	P05	P06	P11	L
C01	4	2	1	2	4	1		