

İzmir Institute of Technology

Faculty of Engineering Mechanical Engineering BS

ME352	SYSTEM ANALYSIS AND CONTROL					
Semester Course Unit Code		Course Unit Title	L+P	Credit	Number of ECTS Credits	
6	ME352	SYSTEM ANALYSIS AND CONTROL	4	4	5	
Mode of Delivery:						

Face to Face Language of Instruction: English Level of Course Unit: First Cycle Work Placement(s): No

Department / Program: Mechanical Engineering BS

Type of Course Unit: Required

Objectives of the Course:

End of this course, the student will able to •model a physical system with its internal dynamics and input-output relationships by means of block diagrams and transfer functions, • generate and use the basic feedback controllers (P,PD,PI,PID), •determine relationships between the parameters of a control system and its stability, accuracy, transient behavior, tracking and disturbance-rejection ability, and parameter sensitivity, •determine the control parameters under the time response for requirements of accuracy, relative stability, and response speed, •determine the frequency response of a control system for evaluating/adjusting the relative stability, response speed, tracking accuracy, and noise rejection ability of the system.

Teaching Methods and Techniques:

Modeling physical systems. Control system components. Transient response. Stability. Steady state response and error. Basic control actions and controllers. Frequency response. Prerequisites and co-requisities:

Course Coordinator:

Name of Lecturers: Asist Prof.Dr. MEHMET İSMET CAN DEDE Assistants:

Recommended or Required Reading

Resources

K. Ogata, "Modern Control Engineering," Prentice Hall, 5th Edition, New Jersey, 2010., R.C. Dorf, R.H. Bishop, "Modern Control Systems," Pearson, 12th

Weekl	y Detailed Course Contents		
Week	Topics	Study Materials	Materials
1 2 3 4 5 6 7	Introduction to Control Systems Laplace Transform System Dynamics with Electrical and Mechanical Components System Dynamics with Hydraulic and Thermal Components Transfer Function, Block Diagram, and Signal-Flow Graphs State Variable Models		R.C. Dorf, R.H. Bishop, "Modern Contro R.C. Dorf, R.H. Bishop, "Modern Contro B.C. Dorf, R.H. Bishop, "Modern Contro
8 9 10 11 12	Transient State Response, Control Parameters Feedback Control, Tuning Controllers Stability of Linear Feedback Systems Root Locus Method		R.C. Dorf, R.H. Bishop, "Modern Contro R.C. Dorf, R.H. Bishop, "Modern Contro
13 14 15 16	Frequency Response Stability in the Frequency Domain Final 1st week Final 2nd week		R.C. Dorf, R.H. Bishop, "Modern Contro R.C. Dorf, R.H. Bishop, "Modern Contro R.C. Dorf, R.H. Bishop, "Modern Contro R.C. Dorf, R.H. Bishop, "Modern Contro
Cours	e Learning Outcomes		
No C01 C02 C03 C04 C05 C06 C07 C08 C09 C10 C11 C12 C13 C14 C15 C15 C15 C15 C15 C16 C10 C10 C07 C07 C07 C07 C07 C07 C07 C0	Learning Outcomes Ability to identify the components and the inputs of a physical system Ability to model the components of a system as linear elements and to write the Ability to draw block diagrams and to obtain transfer functions Ability to choose from open-loop (OL) or feedback (FB) control architectures suit Ability to adjust the parameters of a PID control actions suitably for a specified t Ability to identify the parameters of a PID controller and to construct one if necess Ability to identify the parameters that the system is sensitive to Ability to identify the parameters that the system is sensitive to Ability to determine the effect of a control action and its parameters on the accu Ability to determine the effect of a control action and its parameters on the trans- Ability to determine the effect of a control action and its parameters on the trans- Ability to determine the effect of a control action and support Ability to determine the effect of a control action and support Ability to determine the affect of a control action and support Ability to determine the affect of a control action and support Ability to determine the amplitude ratio and the phase shift between the input a Ability to determine the amplitude ratio and the phase angle variations to the time re Ability to determine the control parameters to satisfy the requirements on the from Ability to determine the control parameters to satisfy the requirements on the from Ability to determine the control parameters to satisfy the requirements on the from Ability to determine the control parameters to satisfy the requirements on the from Ability to determine the control parameters to satisfy the requirements on the from Ability to determine the control parameters to satisfy the requirements on the from Ability to determine the control parameters to satisfy the requirements on the from Ability to determine the control parameters to satisfy the requirements on the from Ability to determine the control parameters to sati	constitutive and connectivity equations for them ably for a specified task by acquiring the basic knowledge about th ask by acquiring the knowledge of the effects produced by them sary degree of stability racy sient response state response state response criteria d output sinusoids sponse of the system aquency response	
Progr	am Learning Outcomes		
No	Learning Outcome	······	<u>.</u>
P03 P02 P04 P06 P05 P01 P08	To have the ability to use modern technical tools which are necessary for engine To be able to design a complicated system or device that can satisfy the requirer To have the ability to detect, define, formulize and solve complicated engineerin To have the ability to design experiments, analyze and interpret results in our To be able to choose and apoly modeling and analyzis methods for the encount To have the ability to modeling and solving engineering problems, using the aco To have the ability to construct verbal and written communication in educational	ering applications and to efficiently implement information technolo ments under realistic conditions; to have the ability to use modern g problems. to examine engineering problems. red problems. uired information about math, science and engineering subjects.	gles. design methods for that purpose.

To have the ability to construct verbal and written communication in educational ianguage. To have the ability to work in disciplinary and interdisciplinary teams efficiently. To be able to act conscious for the necessity of innovation and lifetime-learning; to have the ability of self-renewal and to follow the progress. To be able to have tendency to the applications in professional life and creativity. To have the ability to act with a sense of professional and ethical responsibility; and with environmental and safety concerns. P07 P09 P11 P10

Assessment Methods and Criteria		
In-Term Studies	Quantity	Percentage
Midterm exams	2	%40
Quizzes	3	%15
Homeworks	0	%0
Other activities	0	%0
Laboratory works	0	%0
Projects	1	%15
Final examination	1	%30
Total		%100

ECTS Allocated Based on Student Workload				
Activities	Quantity	Duration	Total Work Load	
Weekly Course Time	1	56	56	
Outside Activities About Course (Attendance, Presentation, Midterm exam,Final exam, Quiz etc.)	1	52	52	
Application (Homework, Reading, Self Study etc.)	0	0	0	
Laboratory	0	0	0	
Exams and Exam Preparations	1	12	12	
Total Work Load			120	
ECTS Credit of the Course			4	

Contribution of Learning Outcomes to Programme Outcomes	
Contribution: 0: Null 1:Slight 2:Moderate 3:Significant 4:Very Significant	
P01 P02 P03 P04 P05	

Contribution. 0. Null 1.5light 2.14					
	P01	P02	P03	P04	P05
C01	4	3	2	2	2
C02	4	3	2	2	2
C03	2	2	2	4	3
C04	2	2	2	4	3
C05	2	2	2	4	3
C06	2	2	2	4	3
C07	2	2	2	4	3
C08	2	2	2	4	3
C09	2	2	2	4	3
C10	2	2	2	4	3
C11	2	2	2	4	3
C12	2	2	2	4	3
C13	2	2	2	4	3
C14	2	2	2	4	3
C15	2	2	2	4	3